

**Oldenburger 3D-Tage, 31.01.–01.02.2024**

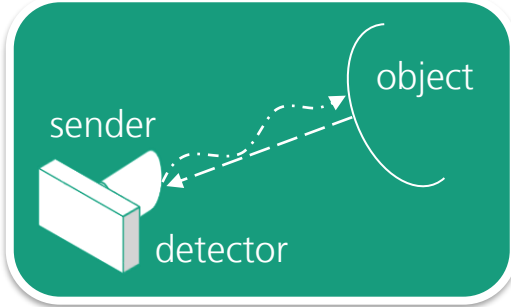
# Thermal single-shot 3D shape measurement of transparent objects with projected spatial- statistical pattern

Henri Speck, Martin Landmann, Andreas Breitbarth,  
Stefan Heist, Peter Kühmstedt, and Gunther Notni

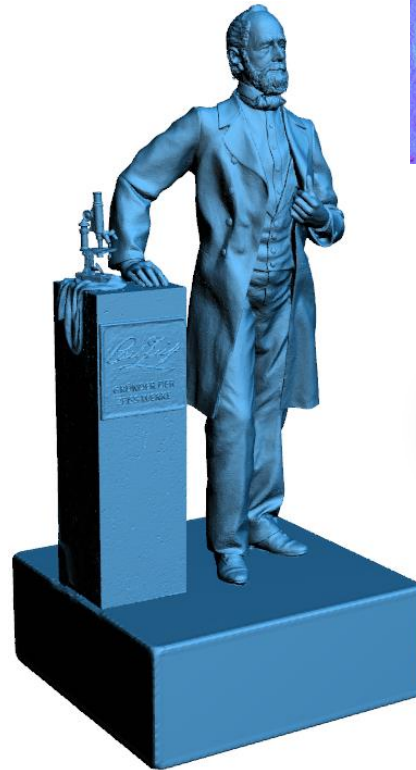
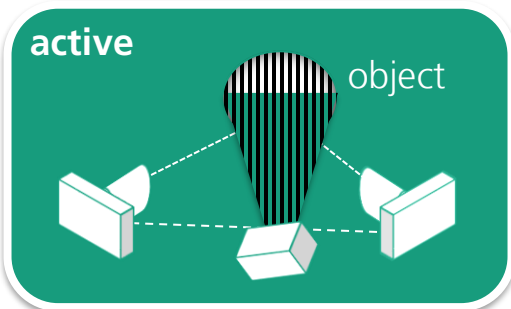
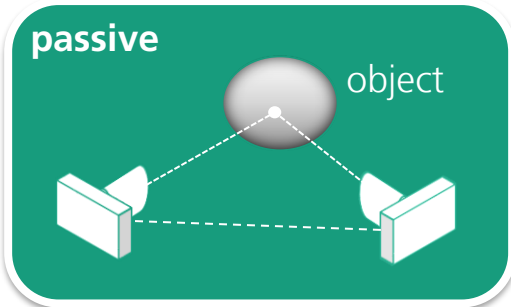
# 3D Measurement Techniques

## State-of-The-Art Optical Methods

time of flight



triangulation



cultural heritage

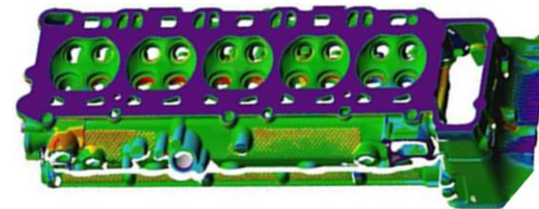


security and forensics

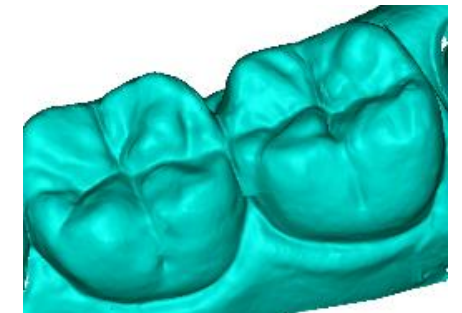


3D sensor network for patient monitoring

diffuse reflection



industrial metrology



medical engineering

# Why Do We Need Thermal 3D Measurements?

## 3D Measurement of Transparent Objects



### 3D surface model

#### conventional VIS 3D sensor



plastic cap measurable  
diffuse reflection

transparent glass *not* measurable  
diffuse reflection

#### thermal 3D sensor



measurement time

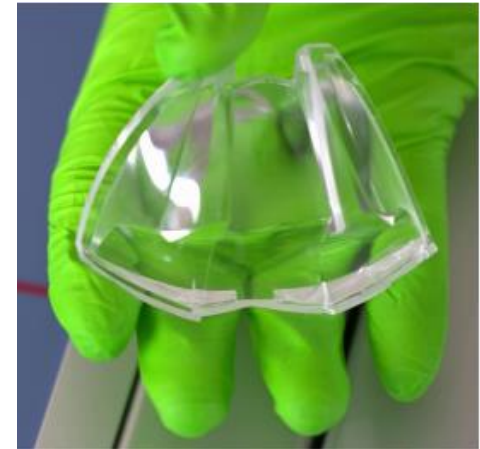
$$t_{\text{meas}} = 4 \text{ s}$$

#### motivation

developing a **single-shot**  
**high-speed** 3D sensor for  
**uncooperative** surfaces

# Why Do We Need Thermal 3D Measurements?

## 3D Measurement of Transparent Objects



# Outline

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**motivation**



**thermal 3D measurement methods**



**simulation results single-shot**



**measurement example**



**summary and outlook**

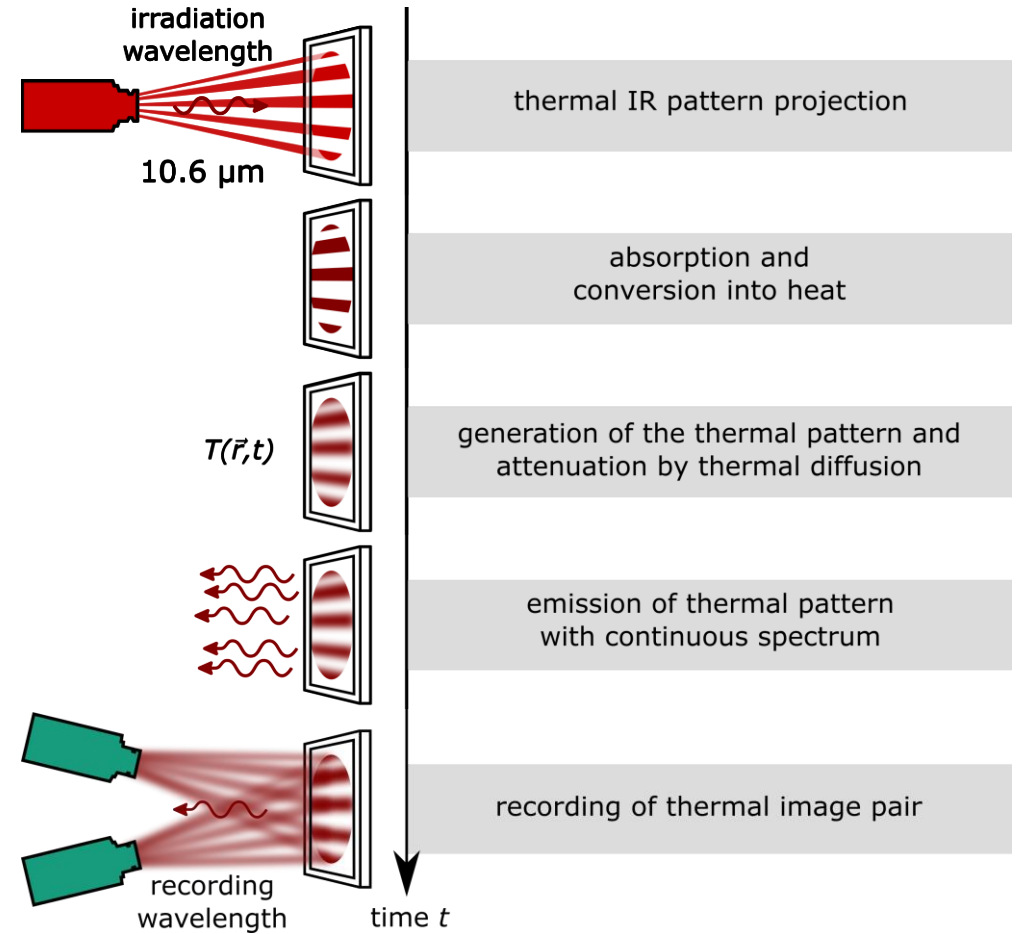
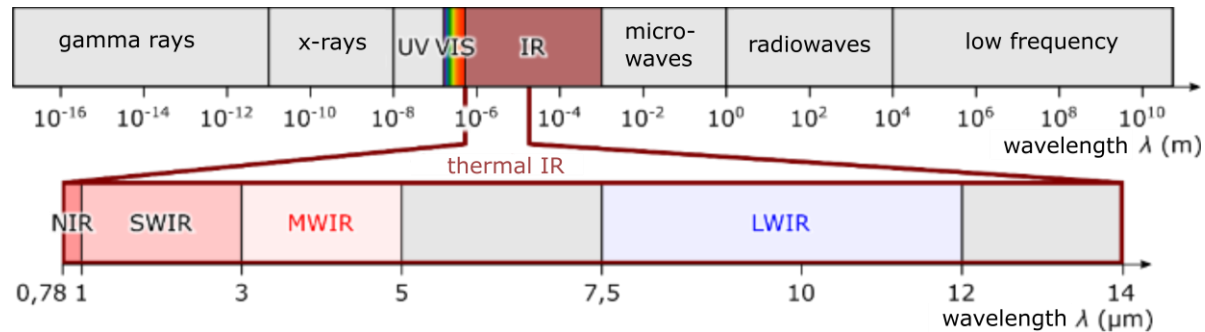
# Measurement Principle: Thermal 3D Measurement

## Projection and Reemission of Thermal Infrared Patterns

pattern projection in VIS (diffuse reflection)



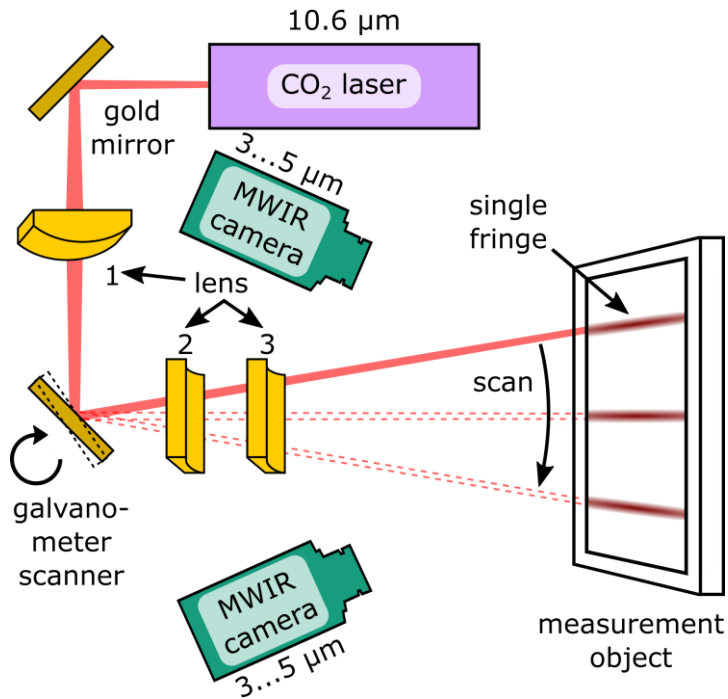
projection and reemission **in thermal IR**



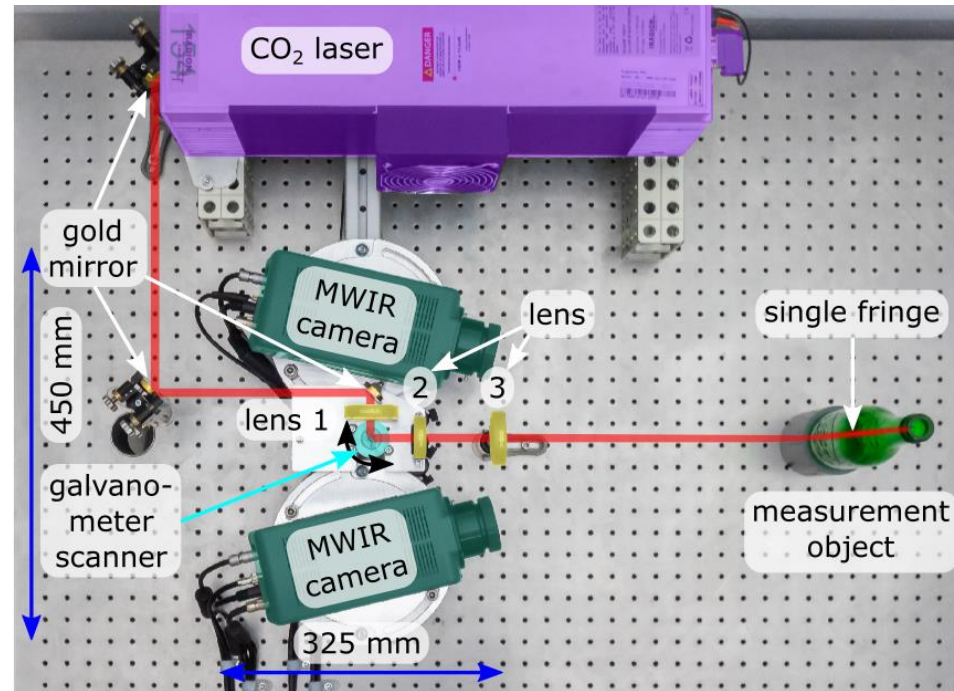
# Realizations of Thermal 3D Sensors

## MWIR 3D Sensor: Sequential Fringe Projection

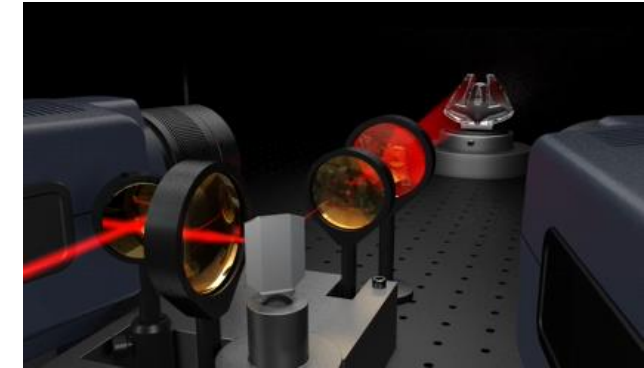
schematic sensor setup



top view of the laboratory setup



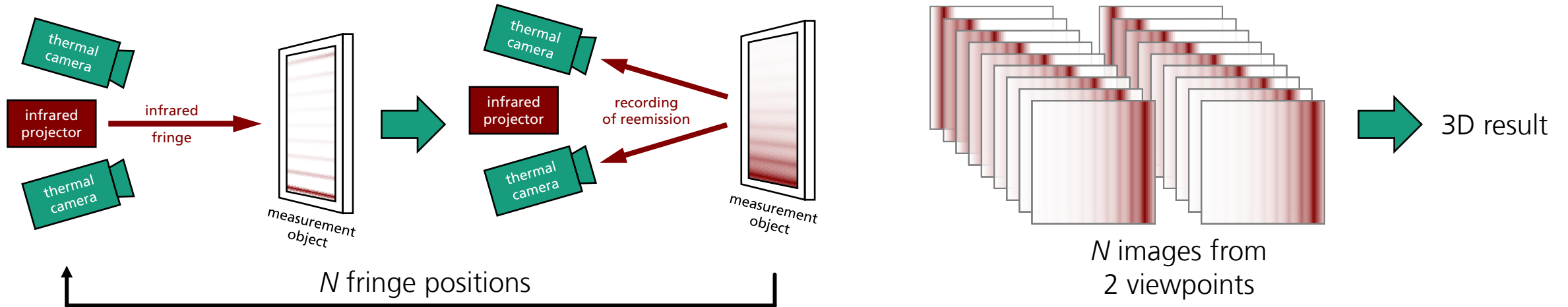
animation



# Measurement Principle: Thermal 3D Measurement

## Projection and Reemission of Thermal Infrared Patterns

projection wavelength: VIS  $\rightarrow$  thermal IR  
detection wavelength: VIS  $\rightarrow$  thermal IR

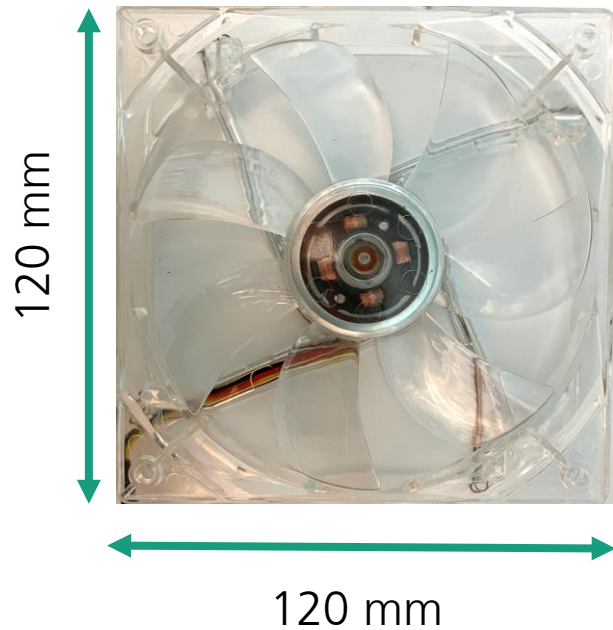




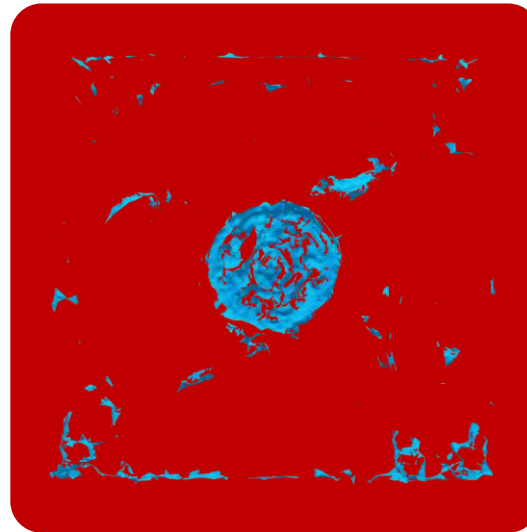
# Realizations of Thermal 3D Sensors

Measurement Example: Fan (not moved)

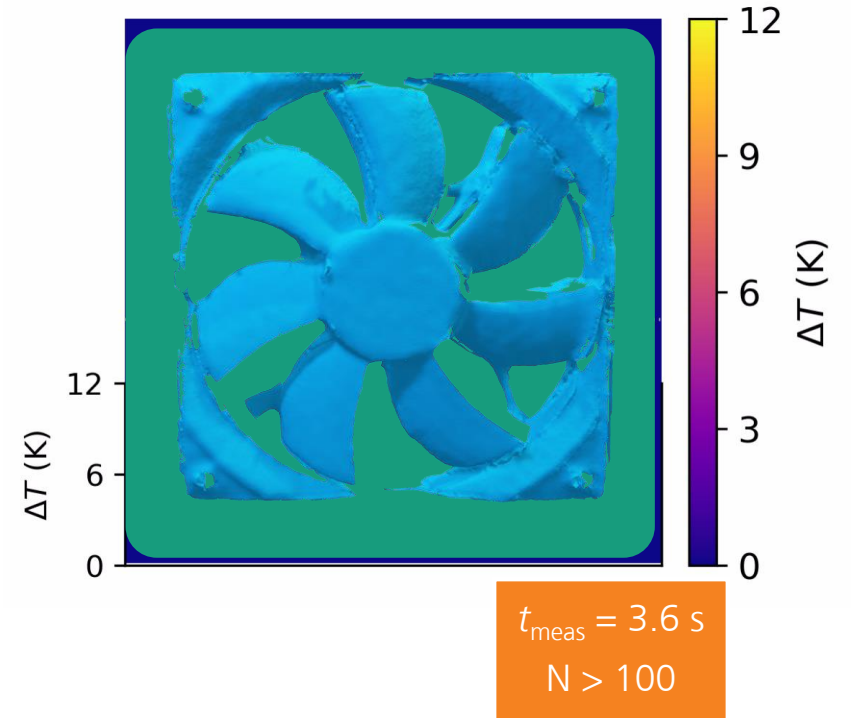
RGB-photo



conventional VIS 3D sensor

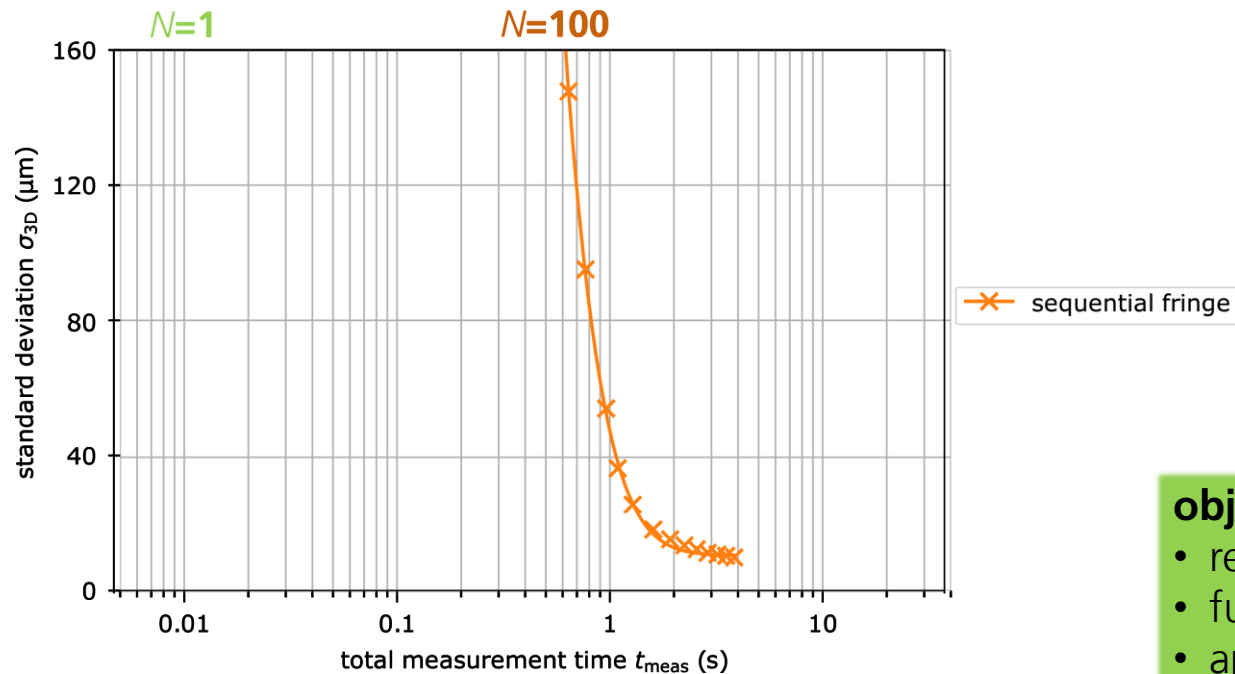


sequential IR fringe projection



# Development Progress from Sequential Fringe Protection to Single Shot

## sensor performance



measurement time  $> 1$  s

→ **too long** for in-line quality control or dynamic processes

**number of images are the limiting factor**

### objective:

- reduction of measurement time to **~10 ms**
- further reduction of influence of **thermal diffusion**
- application for **robot handling, in-line quality control** or **dynamic processes**

# Thermal Single-Shot Approach

## Spatial-Statistical Thermal Point Pattern



diffuse reflection in NIR



**Intel RealSense**  
structured light sensor  
850 nm

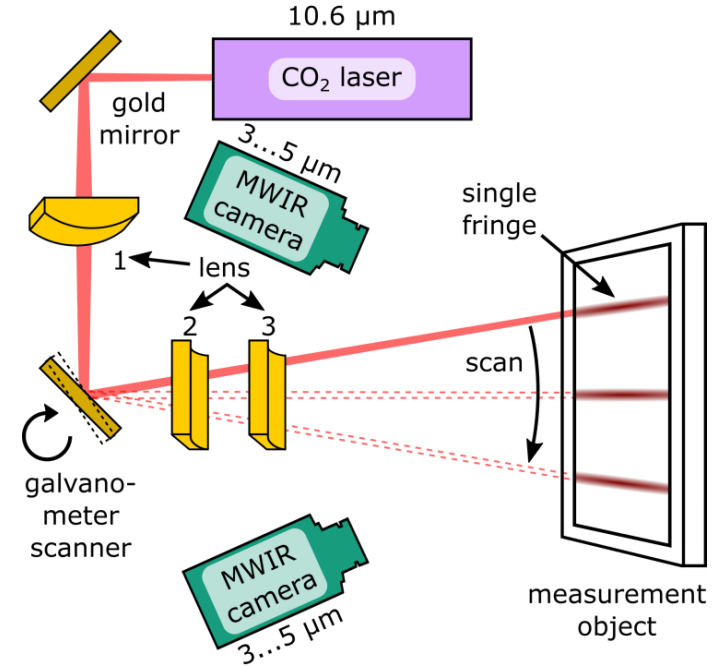


**Apple Face ID**  
structured light sensor  
940 nm



adaption

absorption and reemission in thermal IR



# Thermal Single-Shot Approach

## Spatial-Statistical Thermal Point Pattern



diffuse reflection in NIR



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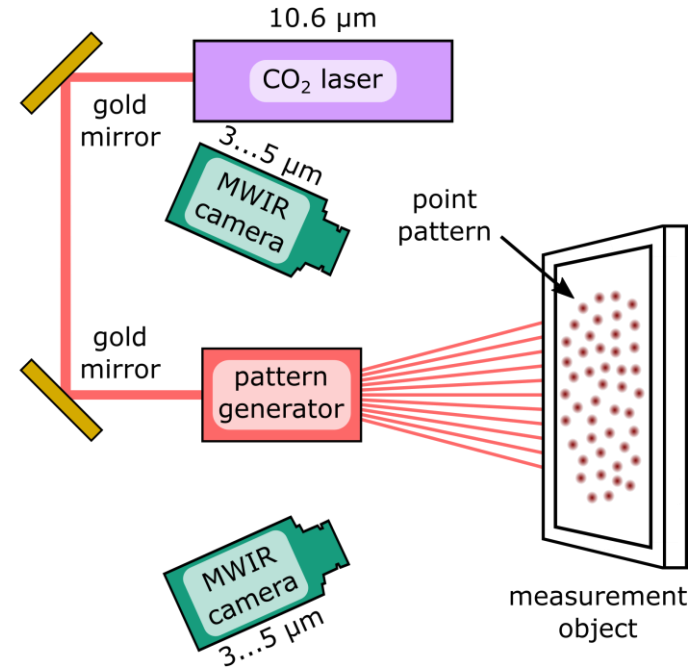


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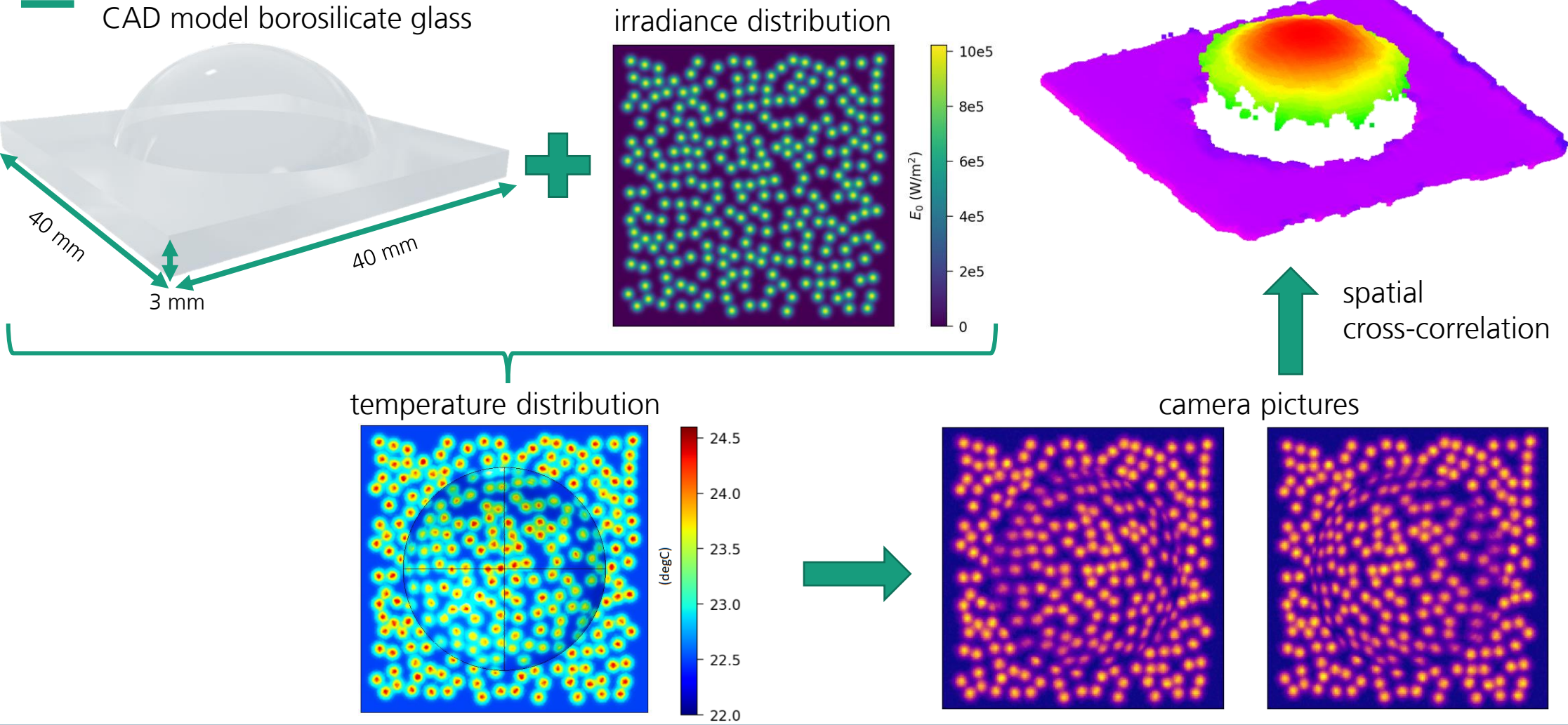
adaption

absorption and reemission in thermal IR



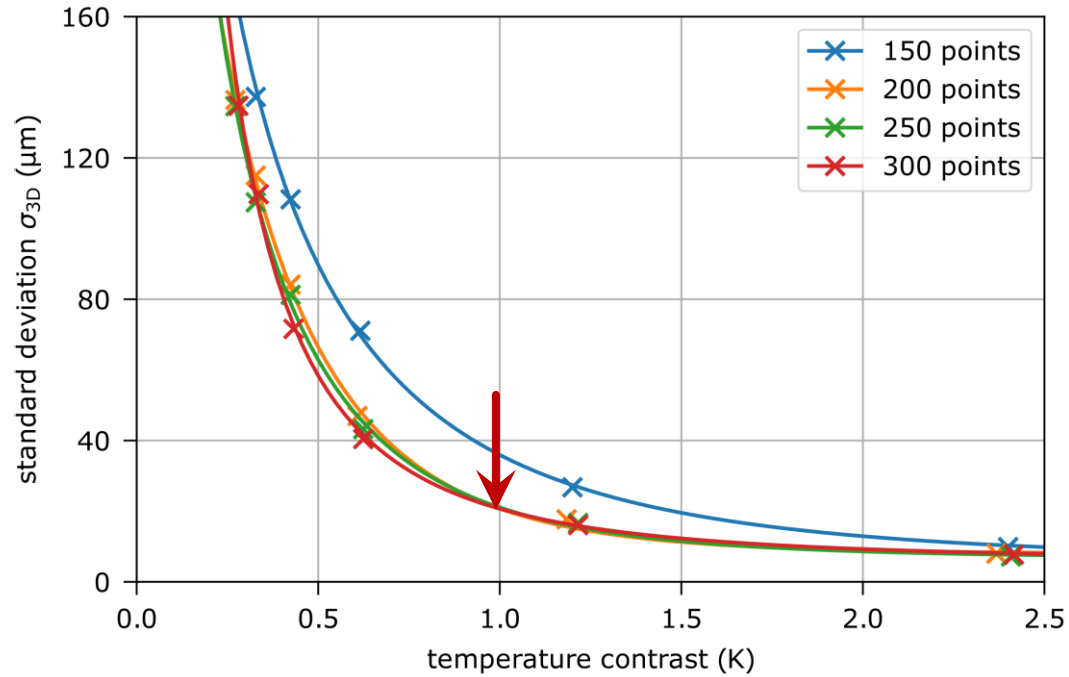
# Thermal Single-Shot Approach

## Simulation Workflow



# Thermal Single-Shot Approach

## Simulation Results: Borosilicate Plane



→  
increasing laser power

temperature contrast:  $\sim 1$  K  
number of points:  $\sim 200$

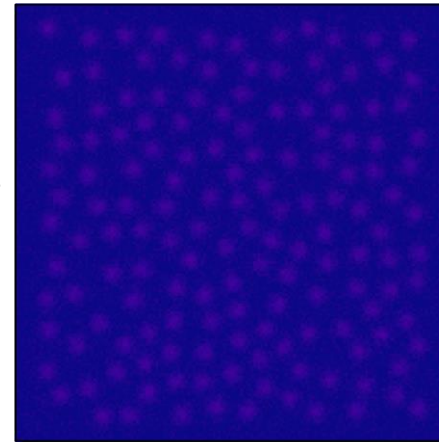
reference



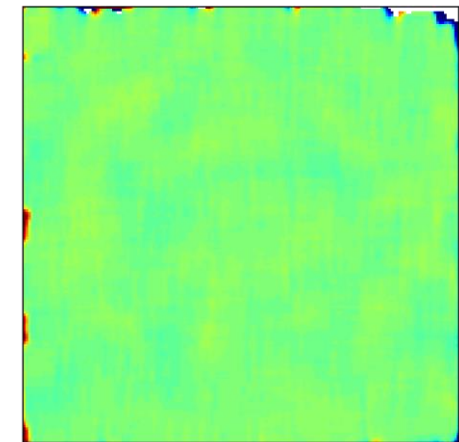
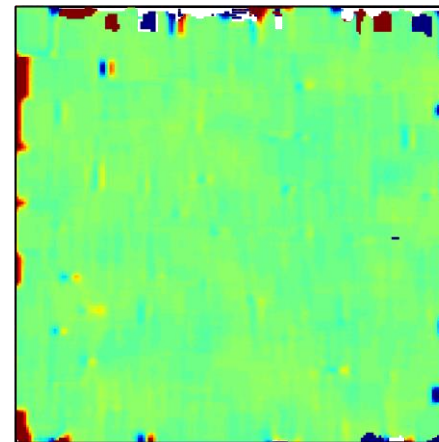
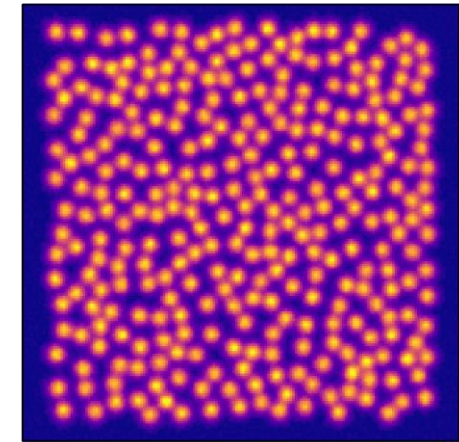
CAD model  
borosilicate plane

temperature contrast: 2.40 K

left camera picture

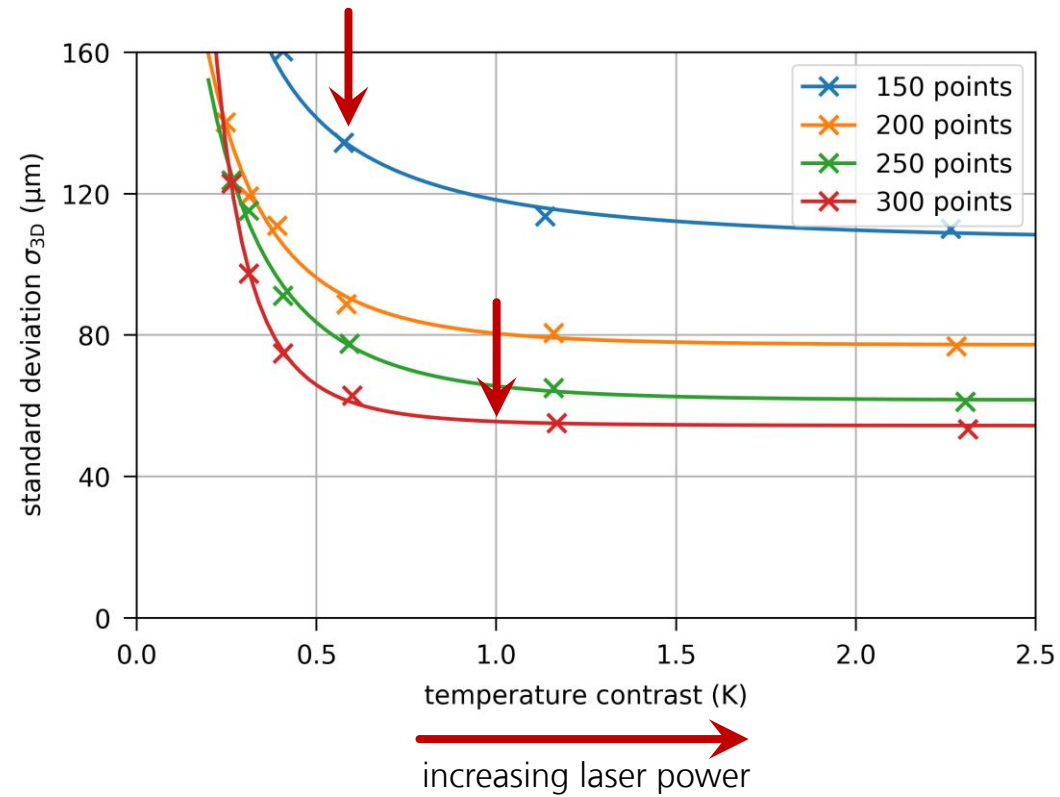


number of points: 300



# Thermal Single-Shot Approach

## Simulation Results: Sphere

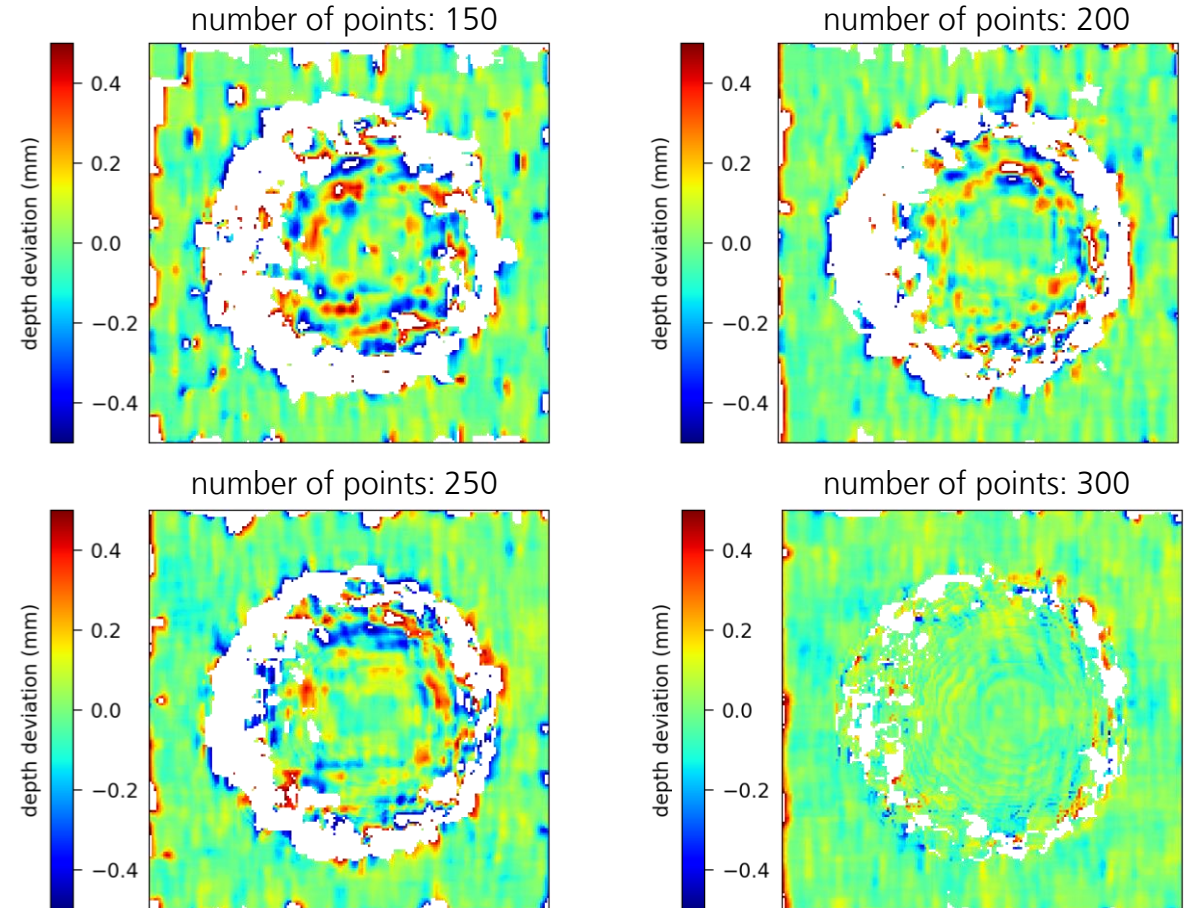


temperature contrast:  $\sim 1$  K  
number of points:  $\sim 300$

reference

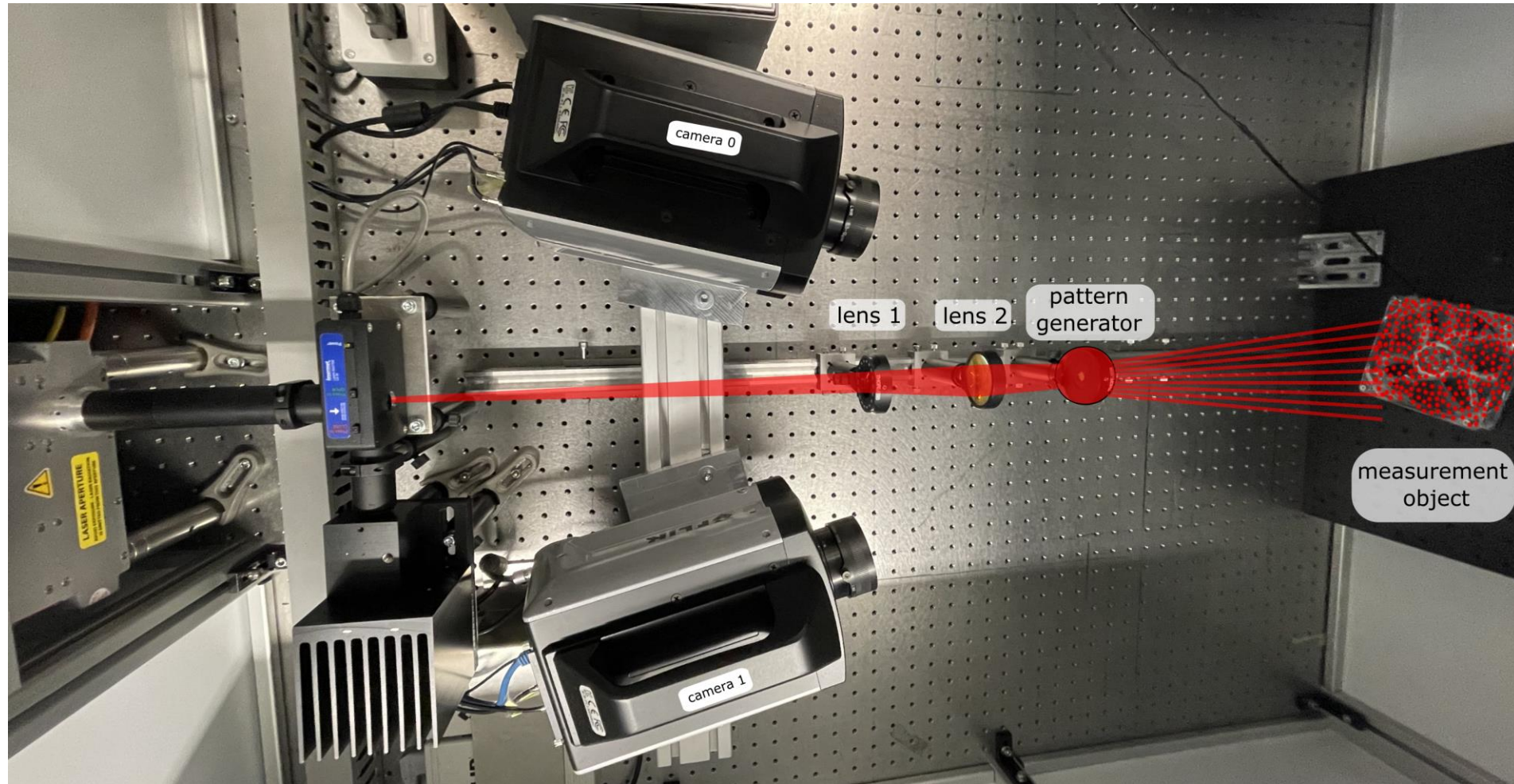


CAD model  
borosilicate sphere



# Realization of Thermal 3D Single Shot Sensor

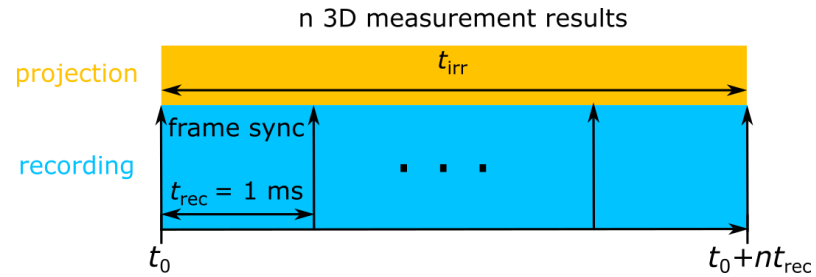
## Experimental Setup





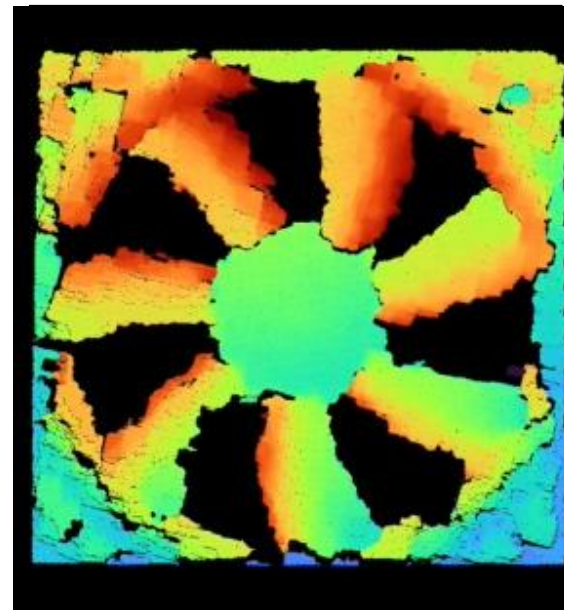
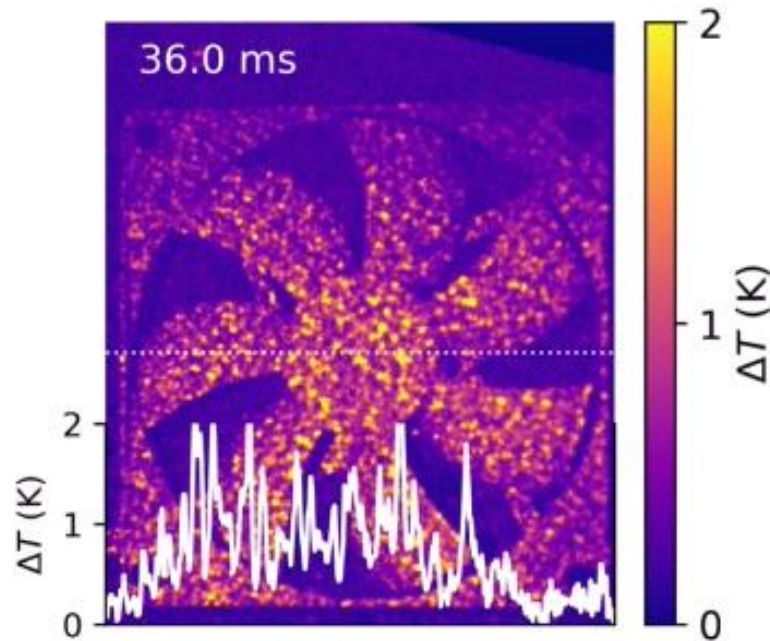
# Realization of Thermal 3D Single Shot Sensor

Measurement Example: Fan (not moved)

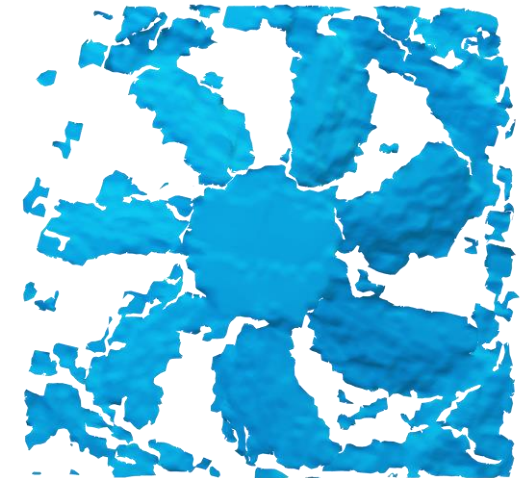


single shot IR projection

3D point cloud



3D surface model



$t_{rec} = 1 \text{ ms}$   $t_{irr} = 10 \text{ ms}$



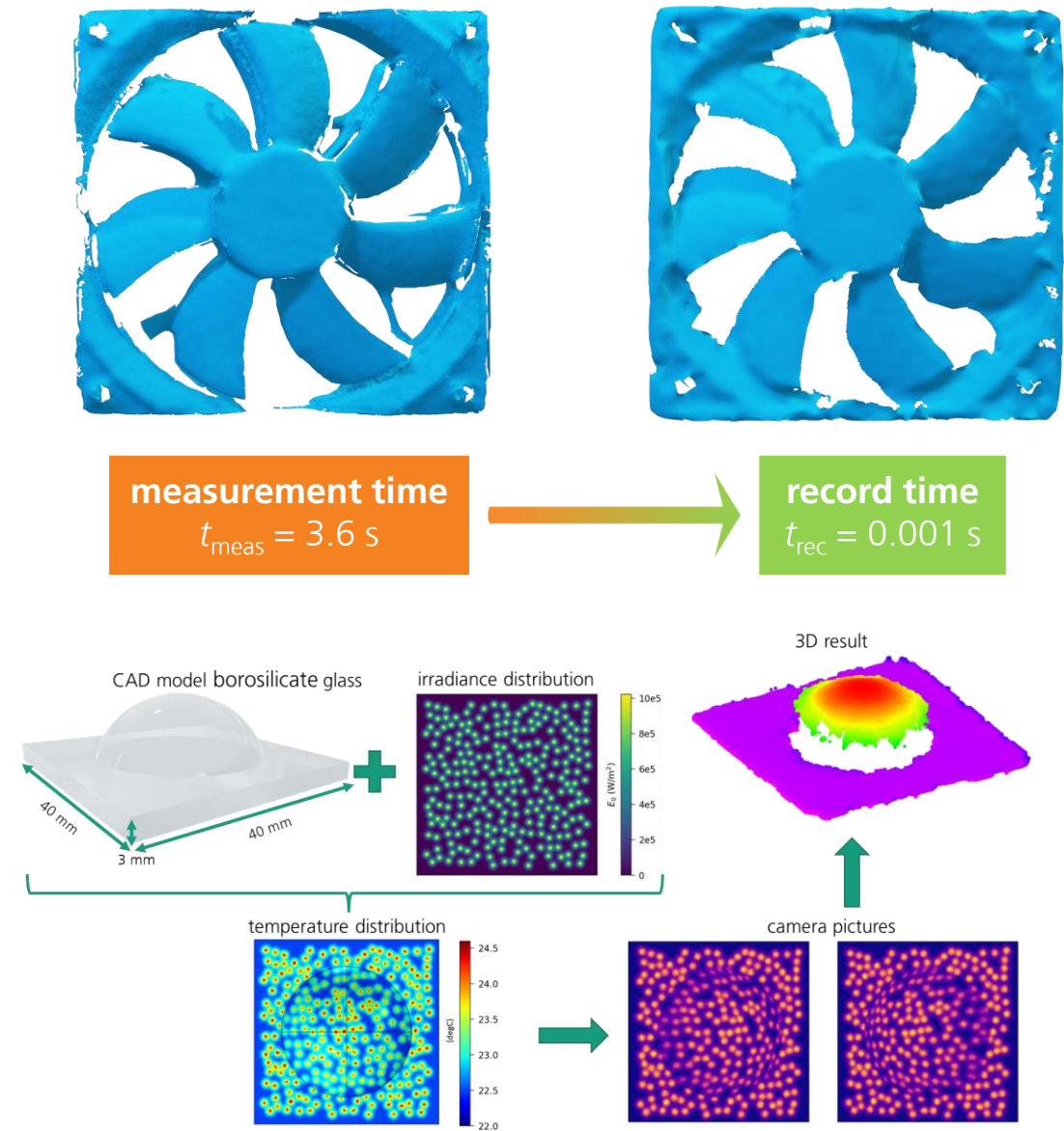
$t_{rec} = 1 \text{ ms}$   $t_{irr} = 36 \text{ ms}$

# Summary & Outlook

## Conclusion

### Results:

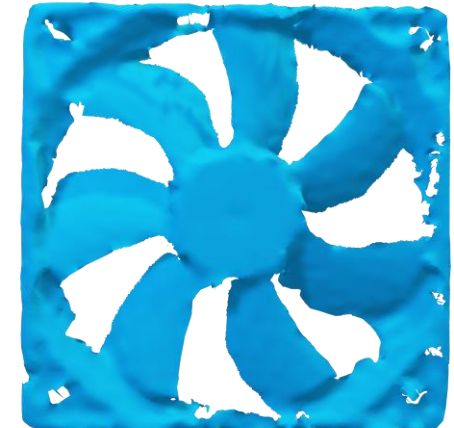
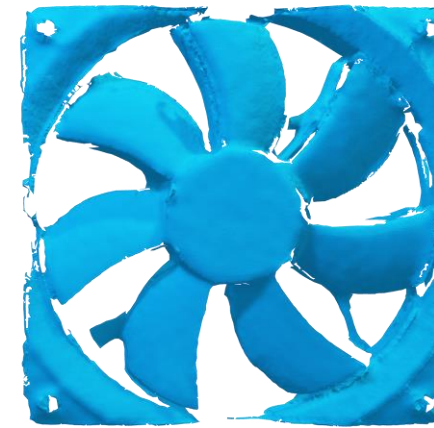
- successful thermal 3D measurements for transparent objects
- build up simulation tool for thermal single-shot 3D measurement
  - temperature contrast of about 1 K
  - point density of about 300 points per  $40 \times 40 \text{ mm}^2$
- realization of experimental setup
- single-shot measurement of a transparent, plastic fan with a repetition rate of 1 ms per 3D results



# Summary & Outlook

## Conclusion

- **Results:**
  - successful thermal 3D measurements for transparent objects
  - build up simulation tool for thermal single-shot 3D measurement
    - temperature contrast of about 1 K
    - point density of about 300 points per  $40 \times 40 \text{ mm}^2$
  - realization of experimental setup
  - single-shot measurement of a transparent, plastic fan with a repetition rate of 1 ms per 3D results
- **Outlook:**
  - experimental realization of a dynamic scene



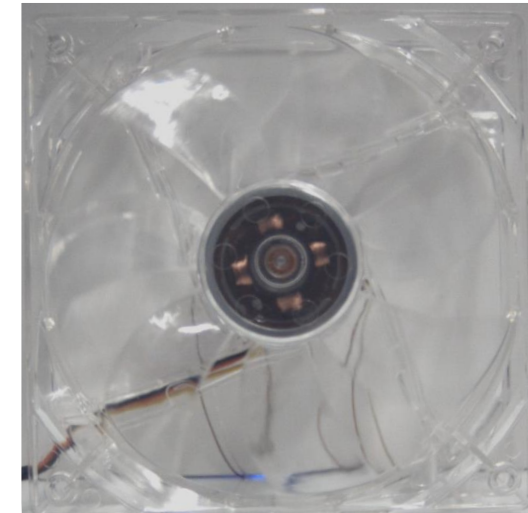
measurement time

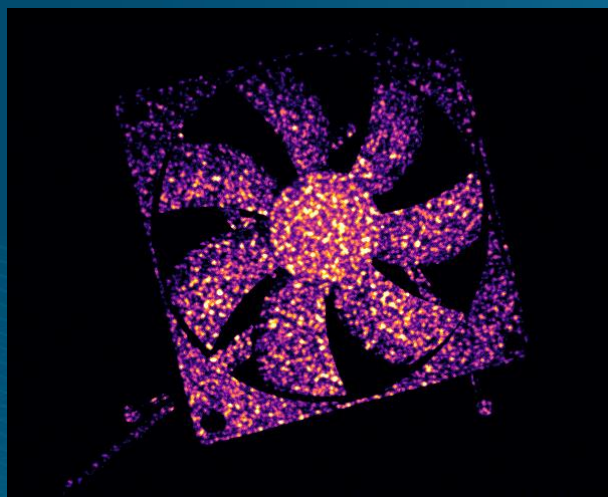
$$t_{\text{meas}} = 3.6 \text{ s}$$



record time

$$t_{\text{rec}} = 0.001 \text{ s}$$





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